

1 Coding (To Metropolize or not?).

Sample from a $\mathcal{N}(0, 1)$ distribution using a 1-d Langevin sampler

$$X_{t+1} = X_t + \delta \frac{d}{dx}(\log \pi(X_t)) + \sqrt{2\delta} \xi_t, \quad \xi_t \in \mathcal{N}(0, 1).$$

- When you change the step size δ , how does the histogram of samples change?
- Now add an acceptance-rejection step. How does the acceptance probability change depending on δ ?

2 Coding (Sampling from a double-well potential).

Apply Langevin dynamics or Hamiltonian Monte Carlo to sample from a double-well potential

$$\pi(x) \propto \exp(-(x^2 - 4)^2).$$

What can you do to optimize? How often does the sampler transition from the right well (centered at $x = +2$) into the left well (centered at $x = -2$)?

3 Coding (Sampling from a doughnut).

Apply Hamiltonian Monte Carlo (HMC) to sample from a doughnut density

$$\pi(x, y) \propto \exp(-(x^2 + y^2 - 25)^2).$$

What can you do to optimize? Is HMC better than Langevin dynamics for this problem?

4 Choose-your-own-adventure (Underdamped Langevin).

The underdamped Langevin equation is the stochastic differential equation

$$d\mathbf{x} = \mathbf{v} dt, \quad d\mathbf{v} = \nabla \log \pi(\mathbf{x}) dt - \gamma \mathbf{v} dt + \sqrt{2\gamma} dW,$$

where \mathbf{v} is the velocity and $\gamma > 0$ is the friction parameter.

- Write down the underdamped Langevin sampling algorithm based on an Euler discretization for the SDE above.
- If we want to correct the bias, how do we define acceptance probabilities?
- Apply underdamped Langevin dynamics to a two-dimensional Gaussian $\mathcal{N}(\mathbf{0}, \Sigma)$ where $\Sigma = \text{diag}(\lambda_{\max}, \lambda_{\min})$ (using math or experiments) and show it can outperform MALA.
- Show that the SDE has a unique stationary measure $(2\pi)^{d/2} \exp(-\|\mathbf{v}\|^2/2) \pi(\mathbf{x})$.

5 Math (No acceleration with Langevin dynamics).

Suppose the target distribution is a two-dimensional Gaussian $\mathcal{N}(\mathbf{0}, \Sigma)$ where $\Sigma = \text{diag}(\lambda_{\max}, \lambda_{\min})$ and we sample using the Langevin sampler. We draw a random velocity according to $\mathbf{v} \in \mathcal{N}(\mathbf{0}, \mathbf{I})$ and apply the update

$$\mathbf{x} \leftarrow \mathbf{x} + \delta \nabla \log \pi(\mathbf{x}) + \sqrt{2\delta} \mathbf{v}.$$

- How is the position $\mathbf{x} = (x_1, x_2)$ updated at each iteration?
- If we want to correct the bias, how do we define acceptance probabilities?
- If we draw samples $\mathbf{x}^{(0)}, \mathbf{x}^{(1)}, \dots$, with $\mathbf{x}^{(0)}$ initialized according to the stationary measure, what is the smallest number of update steps s so that

$$|\rho_1(s)| = |\text{corr}[\mathbf{x}_1^{(0)}, \mathbf{x}_1^{(s)}]| \leq 1/2, \quad |\rho_2(s)| = |\text{corr}[\mathbf{x}_2^{(0)}, \mathbf{x}_2^{(s)}]| \leq 1/2.$$

6 Math (acceleration with Hamiltonian Monte Carlo).

Suppose the target distribution is a two-dimensional Gaussian $\mathcal{N}(\mathbf{0}, \Sigma)$ where $\Sigma = \text{diag}(\lambda_{\max}, \lambda_{\min})$ and we sample using Hamiltonian Monte Carlo (HMC). We draw a random velocity according to $\mathbf{v} \in \mathcal{N}(\mathbf{0}, \mathbf{I})$ and apply L rounds of leapfrog updates:

$$\mathbf{v} \leftarrow \mathbf{v} + \frac{\delta}{2} \nabla \log \pi(\mathbf{x}), \quad \mathbf{x} \leftarrow \mathbf{x} + \delta \mathbf{v}, \quad \mathbf{v} \leftarrow \mathbf{v} + \frac{\delta}{2} \nabla \log \pi(\mathbf{x}).$$

- Show that the position $\mathbf{x} = (x_1, x_2)$ and velocity $\mathbf{v} = (v_1, v_2)$ are updated according to

$$\begin{pmatrix} x_i \\ v_i \end{pmatrix} \leftarrow \begin{pmatrix} 1 - \alpha_i & \delta \\ -\frac{1}{\delta}(2\alpha_i - \alpha_i^2) & 1 - \alpha_i \end{pmatrix}^L \begin{pmatrix} x_i \\ v_i \end{pmatrix},$$

where $\alpha_i = \delta^2/(2\lambda_i)$ for $i = 1, 2$.

- How large can we take δ to ensure a stable algorithm?
- If we want to correct the bias, how do we define acceptance probabilities?
- Show that the samples $\mathbf{x}^{(0)}, \mathbf{x}^{(1)}, \dots$ satisfy

$$\mathbb{E}[\mathbf{x}^{(t)} | \mathbf{x}^{(t-1)}] = \begin{pmatrix} \cos(L \arccos(1 - \alpha_1)) & \\ & \cos(L \arccos(1 - \alpha_2)) \end{pmatrix} \mathbf{x}^{(t-1)}.$$

- Set $\delta = \sqrt{2\lambda_{\min}}$ and set L to be the smallest odd number such that $\cos(\pi/(2L)) \geq 1 - 1/\kappa$, where $\kappa = \lambda_{\max}/\lambda_{\min}$. Then, show the number of leapfrog steps is bounded by

$$L \leq \pi \sqrt{\kappa/8} + 2$$

and the decay of correlations (under the stationary measure) is bounded by

$$0 \leq \rho_1(s) = \text{corr}[\mathbf{x}_1^{(0)}, \mathbf{x}_1^{(s)}] \leq (\sqrt{3}/2)^s, \quad \rho_2(s) = \text{corr}[\mathbf{x}_2^{(0)}, \mathbf{x}_2^{(s)}] = \delta(s).$$

This is an example of *acceleration*, where the amount of work to sample from a poorly scaled distribution only depends on $\sqrt{\kappa}$, not κ .